



EXCERPT FROM THE
PROCEEDINGS
OF THE
FIFTH ANNUAL ACQUISITION
RESEARCH SYMPOSIUM

JOINT ROBOTICS PROGRAM

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by

Joel Brown and Paul Varian

**5th Annual Acquisition Research Symposium
of the Naval Postgraduate School:**

**Acquisition Research:
Creating Synergy for Informed Change**

May 14-15, 2008

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**ACQUISITION RESEARCH PROGRAM
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Proceedings of the Annual Acquisition Research Program

The following article is taken as an excerpt from the proceedings of the annual Acquisition Research Program. This annual event showcases the research projects funded through the Acquisition Research Program at the Graduate School of Business and Public Policy at the Naval Postgraduate School. Featuring keynote speakers, plenary panels, multiple panel sessions, a student research poster show and social events, the Annual Acquisition Research Symposium offers a candid environment where high-ranking Department of Defense (DoD) officials, industry officials, accomplished faculty and military students are encouraged to collaborate on finding applicable solutions to the challenges facing acquisition policies and processes within the DoD today. By jointly and publicly questioning the norms of industry and academia, the resulting research benefits from myriad perspectives and collaborations which can identify better solutions and practices in acquisition, contract, financial, logistics and program management.

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Joint Robotics Program

Presenter: Joel Brown, Defense Acquisition University

Author: Paul Varian, Project Manager, Robotics Joint Project

Introduction

Sun Tzu wrote first about the importance of logistics over two thousand years ago (Griffith, 1963, pp. 72, 74),¹ followed by Von Clausewitz 150 years ago—who again echoed the importance of logistics to overall mission success (Greene, 1943, pp. 136, 179)²; now, logistics is a *Defense Acquisition Workforce Improvement Act* functional area. Since Sun Tzu, much literature, many experiments, lessons learned, and the DoD's continual searching for better logistics answers have stressed the continued importance of getting the right things to the right place at the right time. Much like human transportation history evolution—beginning first with people walking or running from point a to point b, followed by thousands of years being transported by real “horse” power, then automobiles, airplanes, and rockets—logistics too has progressed over the years: focusing first on Mass-based Supply, then Just-in-Time Supply Chain Management, and now on Sense and Respond logistics.

The Robotic Systems Joint Project Office (RSJPO), an Army-Marine Corps effort that supplies various robots to the AORs of Iraq and Afghanistan, has also evolved through the three logistics methods. During each approach, many positive benefits were discovered. Along with those benefits, there were and are still today challenges to be confronted and overcome. The Robotics Program’s experience and lessons learned since it began “real time” theater support in 2003 can aid all logistics programs by exemplifying the better ways to provide the best logistics with the knowledge, skills, and tools available today. All logistics functions, as shown by the Robotics Program, can be provided incredibly fast, quite inexpensively, and with superior quality and customer satisfaction.

Mass-based Inventory

For many long years, logistics relied on provisioning and sparing as the logical answer to supporting any weapons system. Numerous logisticians were trained in the art and science of sufficient inventory and spares, which would keep systems functioning for the fielded units anytime and anywhere. Budgets were predicated against these projected numbers. Many logisticians established careers tracking, analyzing, projecting, adjusting, and readjusting Mass-based Support for all weapons systems. This logistics approach did provide weapons system support that could function appropriately in the field (Van Creveld, 1977, pp. 206, 214). Warfighters (customers) were required to learn which spares were critical and in what numbers, while also trying not to have too much inventory of all the wrong things lying about taking up needed space and expending too much available budget. The robotics program first began by

¹ Sun Tzu gives the projected costs for supporting war efforts as well as stating logistics for his time equated to 60% of the total costs incurred.

² Von Clausewitz surmises total war requires everything relates, including logistics, to providing the soldier at the right place at the right time to be perfectly effective.



utilizing Mass Based logistics to support the initial fielding of 162 robots. Since the majority of suppliers were small businesses (in DoD parlance, “Mom & Pops”) and were finding it difficult to spare or keep up with production, the Program Manager declared that a portion of the total available robots would function as spares. Central Command (CENTCOM) controlled all robots as theater-provided equipment (TPE), rather than granting one of the Services total ownership. However, as the robots were fielded, Command found that the robots worked exceptionally well and replaced warfighters in critical danger missions. The Services would not release critical robotic assets and demanded many more robotic platforms be sent into the field. Very quickly, CENTCOM and the Project Manager realized Mass Based Logistics would not support well the customer’s demand. Another logistics approach was quickly required. What support program would allow the small businesses to produce, supply, and keep up with an ever-increasing field demand?

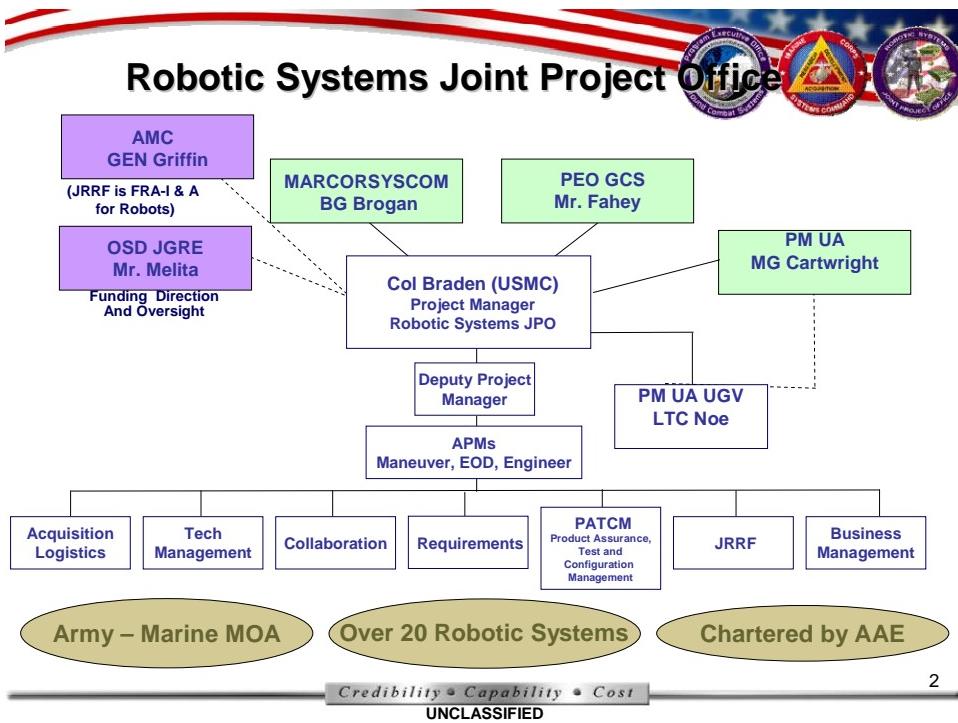
Just-in-Time

Just-in-Time (J-I-T) logistics support promised to better align suppliers with customers in providing the right item at the right time in the right place. J-I-T also promised to reduce inventories and spares to near zero. In order to achieve these objectives, quality would need to be more strictly monitored; deliveries would need to be timed better; suppliers would need real-time communication with the customers’ system to better predict when they needed to provide needed items. Production needed to be stable so suppliers could more easily meet demand (Kotler, 1997, pp. 214-215). The Robotics program moved toward J-I-T within six months as Massed-based supply could not keep up. The Project Manager and Suppliers gathered data on which robotic parts lasted or failed and how often. Often, the same supply approach (one new robot for one damaged or eliminated robot) was carried over from the Mass-based Approach. Rebuilding damaged robots grew from the J-I-T approach. Both the Project Manager and the Robotic Suppliers needed faster and more accurate information each day. Tracking robots and their status and location in the field became a pressing point. No in-house DoD information system existed to provide this ever-increasing communication need. The Project Manager partnered with Avantix and T&W Communications to create the Catalog Ordering Logistics Tracking System (COLTS) program. The program utilizes UID formats and capabilities to provide the Project Office, as well as the suppliers, with critical, daily information to meet the warfighters’ demands. The J-I-T approach provided more accurate robot fielding. Separate warfighter units only received robots that were truly mission required, rather than potentially hoarding robots as back ups. The logistic footprint was reduced as robots were repaired, rebuilt, or supplied as needed. The biggest challenge for the Robotic Project with J-I-T was caused by interruptions or breaks in the transportation chain—disruptions to the process of getting required robots to their place of need. This is a story we’re all familiar with in air travel: one weather delay for the airlines causes a major ripple effect to all airlines and passengers trying to get to the right place at the right time. Once again, the Robotics Program needed another improved logistics solution!

Sense and Respond

This Sense and Respond section will flow from a TAV brief given at TACOM in Winter 2007 by the current Robotics Program Manager (Varian, 2007). Sense and Respond logistics arose from the inability of J-I-T to completely satisfy the warfighter customer.

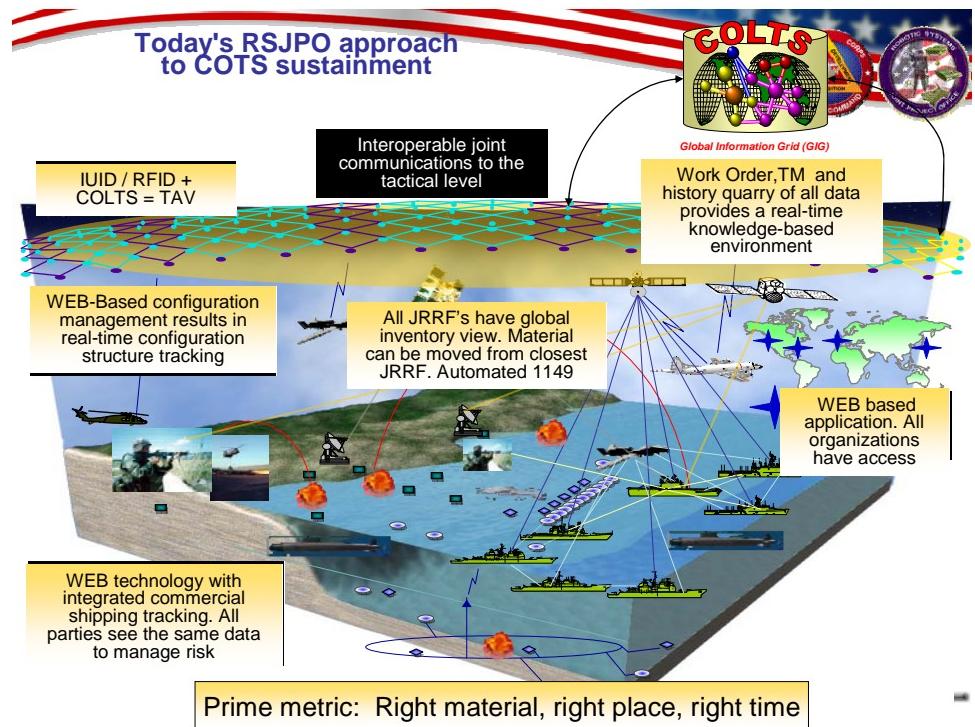




The relationship/JPO chart shows how the Robotics System Joint Program fits into the joint Army/Marine PEO. Joint Robot Repair Fielding (JRRF) is just one of the areas necessary for total Program success.



The above graphic relates the Robotic program and explains how the customers' needs continue to rapidly expand. The Program has instituted no more than four hours for any robotic replacement, anywhere, anytime.



The figure above relates how the COLTS software program specifically helps achieve the overall goals for Sense and Respond. It is the full implementation of COLTS that allows IUID/RFID to provide a Total Asset Visibility (TAV). To facilitate Sense and Respond, TAV and real-time information flow will be critical to sustainment of tomorrow. The following chart provides the driving tenets for all people involved with the Sense and Respond Robotics logistics support.

What Joint Robotics Repair Facility Is Doing



1. Define the **WAR-FIGHTER**: As the private or crew member in the heat of it.

2. Understand what is important to the **WAR-FIGHTER**:

Time
Equipment that works
Time

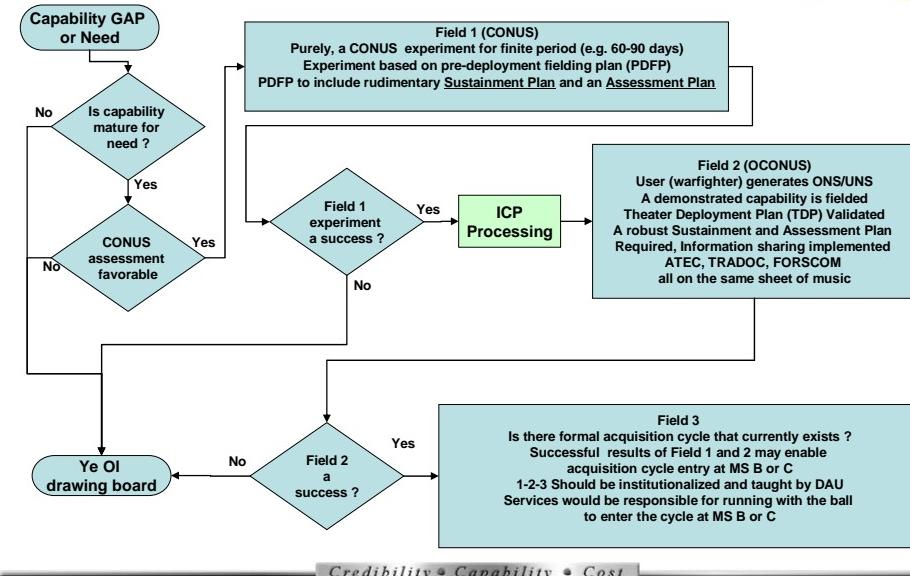
3. Define PBL in a term the **WAR-FIGHTER** understands.

We structure our support to be reactive to the private or crew member in the heat of it. The WAR-FIGHTER receives a robot in 4 hours or less. PERIOD

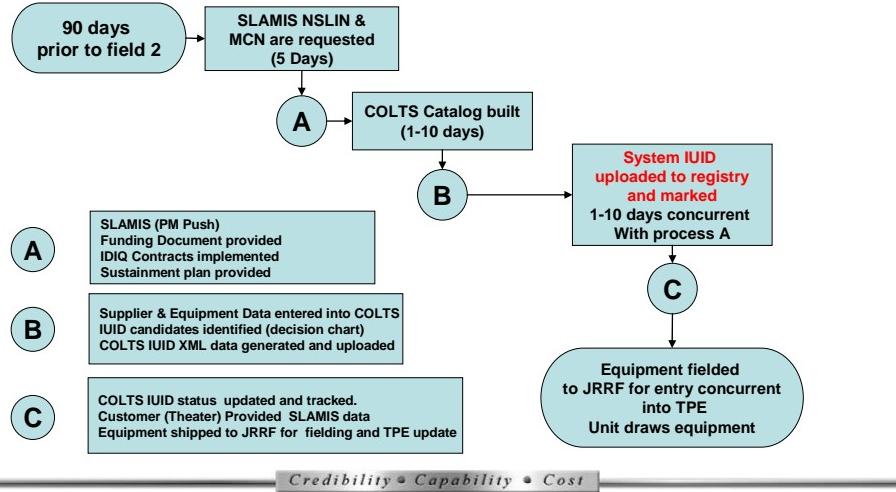
Credibility • Capability • Cost

By defining processes, the following charts illustrate how the Robotics Program office achieves the above program goals.

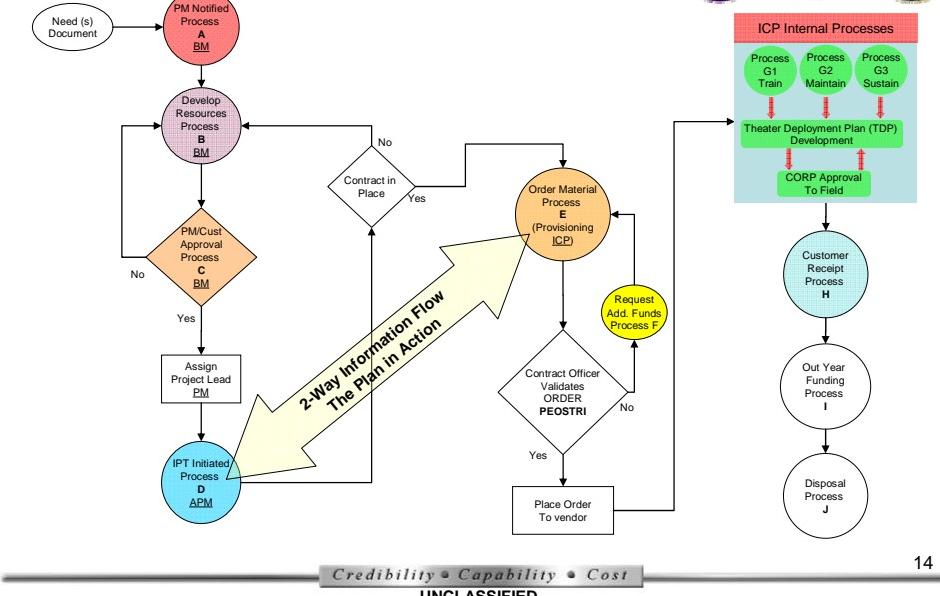
1,2,3, Process Flow



Inventory Control Point (ICP) Pre-fielding process



The JRRF from 40,000 feet



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The Robotics Program has completely embraced the IUID (Item-unique Identification) method and is continually discovering capability benefits from the warfighter all the way to the supplier and back again. The following presents just some of these capabilities.



COLTS (SCM) value to the RSJPO



- Integrated IUID capability. COLTS **USES** the data not just generates the data.
 - Vendors see data and have "buy in" with the IUID process
 - Ability to mark equipment "on site" virtual IUID NOT REQUIRED
- WEB Based centralized database: There is no requirement to "exchange" between databases. It is one stop for common tasks
 - Email notification on trigger events
 - Equipment modification notification generated and tied to equipment
 - All stake holders have access to the data and all see the same thing
 - Data exportable to Excel™ and data interchange is possible i.e. DAASC, ULLS, etc.
 - Reports generation automatically or data mine to customize
- Configuration management up to 15 levels
- Consumption tracking:
 - Real-time parts usage and consumption data.
 - Real-time maintenance data (TTR, Man-hours, WO processing, etc)
- 100% Property accountability:
 - All items are assets. As such nothing is "forgotten" items are always "issued" or "transferred" but never forgotten

Credibility • Capability • Cost

We could spend a great deal of time relating what the Robotics program has achieved by presenting numerous charts and graphs of how improvements have been made over the course of the program. But rather than take up valuable time and space, we thought just the bare facts presented below say it all...





Return on Investment

- A misplaced hyphen cost \$280K
- IUID enables Serialized Item Maintenance (SIM is a DoD Mandate)
 - IUID Enables real time configuration management
 - IUID Saves repair parts cost
 - Aug 06-Mar 07 \$29M for repair parts on 1 vendor
 - Aug 07-Mar 08 \$ 5M for repair parts on same vendor
- IUID eliminates human induced error
 - Average human has a typing error rate 5.47%. For every 100 key strokes 6 will be wrong

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Credibility • Capability • Cost

UNCLASSIFIED



Just the facts (1 Jan 07 – 1 Dec 07)

- COLTS Supply & Maintenance Data
 - 6073 Work orders completed
 - 26,375 maintenance actions
 - 64,419 Inventory events (Parts movement)
 - 78,467 Asset events (Robot actions/movement/repair, etc)
 - 4,816 Items shipped
 - 64 EOD/Engineer robots rebuilt from a destroyed condition. Cost savings approximately 3.2 million dollars.
- IUID integration saves the RSJPO time, money and ultimately lives on the battlefield.
 - No more “lost” data due to human error
 - Shorter repair cycle time as a result of IUID “scan in & scan out”
 - More fidelity of data tracked in COLTS due to IUID decision process.
 - Routine logistics processes streamlined with IUID and hand scanner.
 - Configuration management integrated with all SCM actions. SIM is a reality
- Operational rate on all NS-E/COTS supported platforms has been in excess of 98% since Apr 05.
- In excess of 3307 soldiers trained on robotics operation

Credibility • Capability • Cost

What more need we say about Sense and Respond logistics and the benefits it has provided to the warfighter?



Conclusion

Many presenters and numerous authors continue to assert the rate of change in our era will continue to geometrically expand. The Robotics Program since 2003 has rapidly traversed through Mass-based, Just-in-Time, and Sense and Respond logistics approaches, always trying to improve support to the warfighter. Each logistics approach provided benefits and challenges. Each moved into another logistics support scheme built on the previous lessons learned and added new features—with the final goal of reducing the logistics footprint, expending less dollars, and providing the best equipment (which works well when required) to the right warfighter at the right time. The next chart captures each logistic approach and explains why another approach was sought.



Even now, the Robotics Program's Sense and Respond approach is not the final logistics answer. New features (active and passive RFID among others) are being tested, data are being gathered and analyzed, and better processes are being implemented to continually improve the Program's logistics. Other DoD and industry programs should take note and seek out people from this Robotics Program in order to discover better ways to fully support the warfighter. The perfect logistics answer is still to come.

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2003 - 2008 Sponsored Research Topics

Acquisition Management

- Software Requirements for OA
- Managing Services Supply Chain
- Acquiring Combat Capability via Public-Private Partnerships (PPPs)
- Knowledge Value Added (KVA) + Real Options (RO) Applied to Shipyard Planning Processes
- Portfolio Optimization via KVA + RO
- MOSA Contracting Implications
- Strategy for Defense Acquisition Research
- Spiral Development
- BCA: Contractor vs. Organic Growth

Contract Management

- USAF IT Commodity Council
- Contractors in 21st Century Combat Zone
- Joint Contingency Contracting
- Navy Contract Writing Guide
- Commodity Sourcing Strategies
- Past Performance in Source Selection
- USMC Contingency Contracting
- Transforming DoD Contract Closeout
- Model for Optimizing Contingency Contracting Planning and Execution

Financial Management

- PPPs and Government Financing
- Energy Saving Contracts/DoD Mobile Assets
- Capital Budgeting for DoD
- Financing DoD Budget via PPPs
- ROI of Information Warfare Systems
- Acquisitions via leasing: MPS case
- Special Termination Liability in MDAPs



Human Resources

- Learning Management Systems
- Tuition Assistance
- Retention
- Indefinite Reenlistment
- Individual Augmentation

Logistics Management

- R-TOC Aegis Microwave Power Tubes
- Privatization-NOSL/NAWCI
- Army LOG MOD
- PBL (4)
- Contractors Supporting Military Operations
- RFID (4)
- Strategic Sourcing
- ASDS Product Support Analysis
- Analysis of LAV Depot Maintenance
- Diffusion/Variability on Vendor Performance Evaluation
- Optimizing CIWS Lifecycle Support (LCS)

Program Management

- Building Collaborative Capacity
- Knowledge, Responsibilities and Decision Rights in MDAPs
- KVA Applied to Aegis and SSDS
- Business Process Reengineering (BPR) for LCS Mission Module Acquisition
- Terminating Your Own Program
- Collaborative IT Tools Leveraging Competence

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Acquisition Research Program: Creating Synergy for Informed Change

Joint Robotics Repair & Fielding

Mr. Paul Varian
JRRF Division Chief

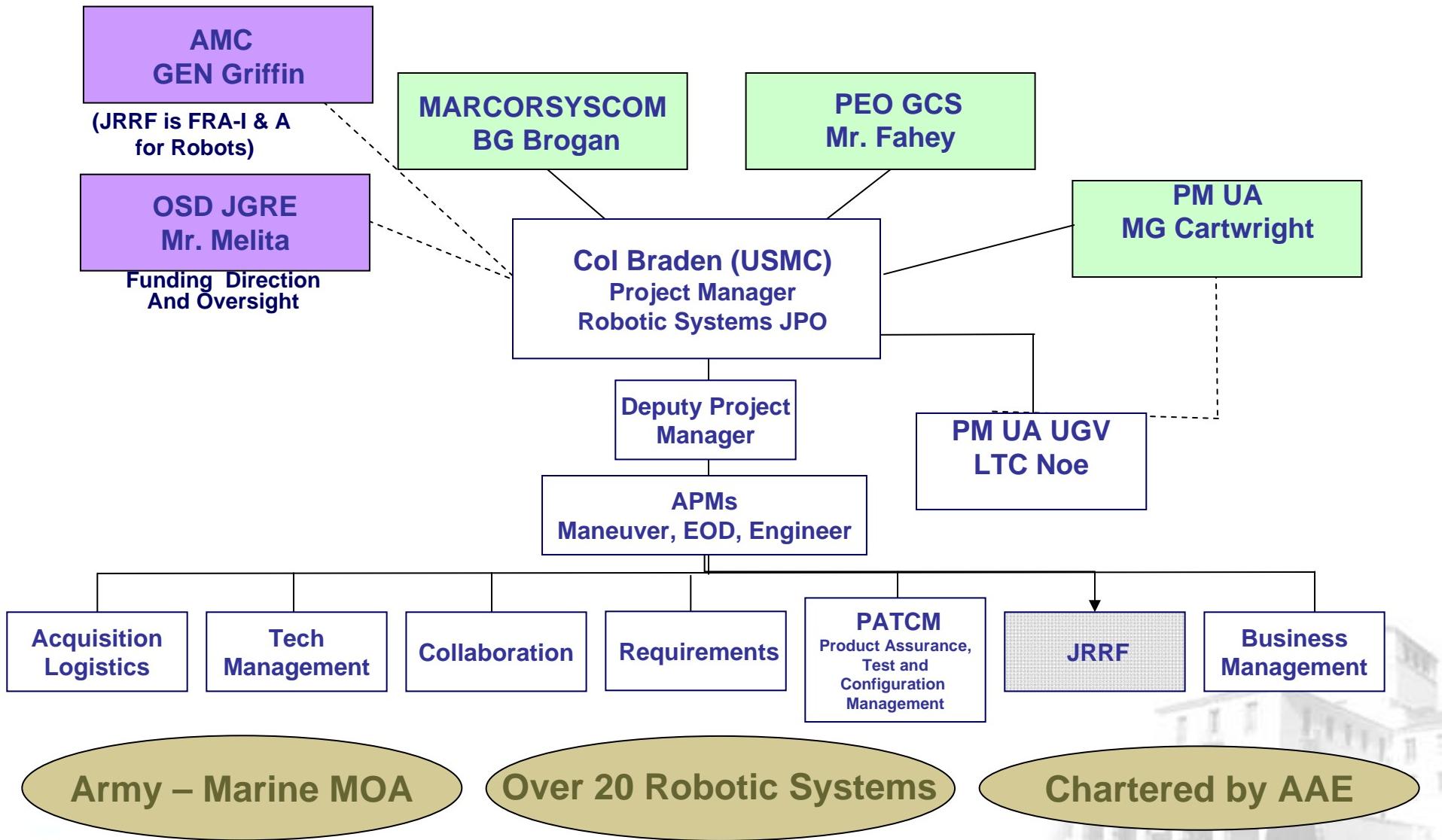
Robotic Systems Joint Project Office



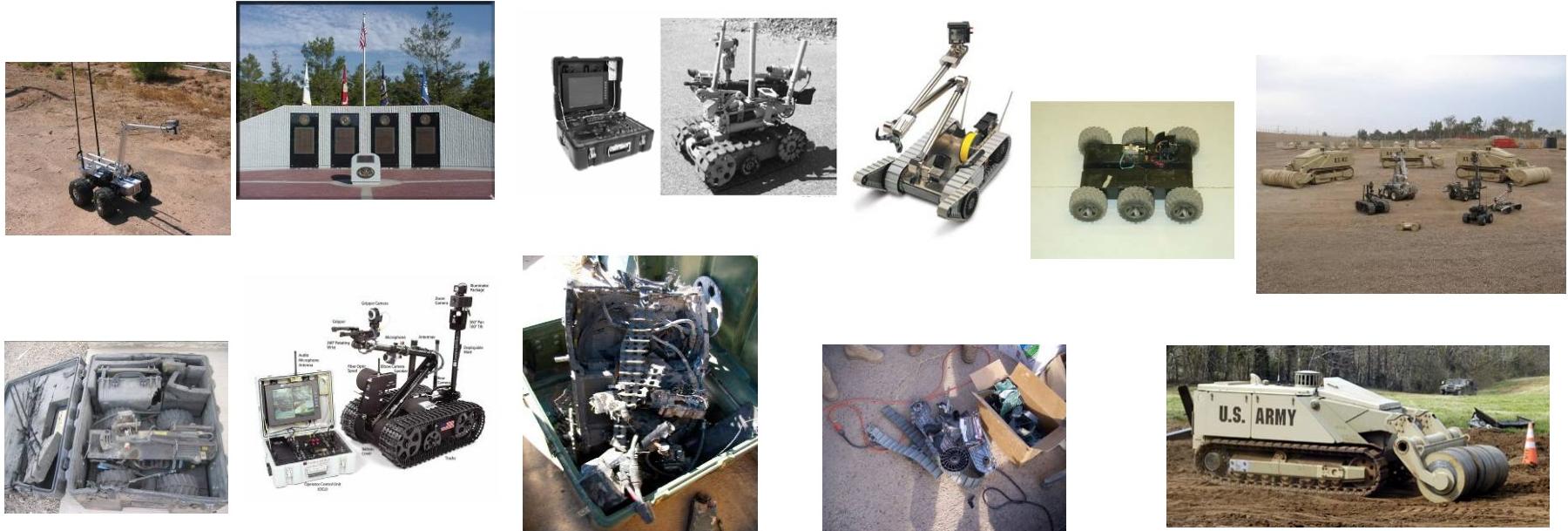
15 May 2008
Mr. Paul Varian



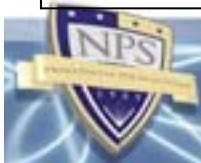
Robotic Systems Joint Project Office



Joint Robot Repair Fielding (JRRF)



- Provide in-Theater Support for Joint Service Theater Provided Equipment (TPE) Ground Robots.
- Single “Belly Button” for OIF/OEF Training, Sustainment, Assessment, and Accountability
 - 162 Bots (2004)
 - 1800 Bots (2005)
 - 4300 bots (Now)
 - 6000+ est'd (2008)
- Pre-Deployment Training Sites JRRTs and Mobile Training Teams – *Joint Reserves* (61%)
- 4 Hour Robot Turn-Around Standard – *Leveraging “Joint Float Pool Concept”*
- Web-Accessible Real-time Supply Chain Management with integrated IUID – *Key step toward sense and respond logistics*
 - Accountability
 - Parts Reordering
 - Reliability Tracking
 - Trouble Desk Info



2007 Measures of Effectiveness (OIF/OEF)

| # of Missions | # of Found & Cleared IEDs | # of Destroyed Robots |
|---------------|---------------------------|-----------------------|
| 25,000 + | 15,037 | 150 |

- **26,000 Robot Maintenance Actions**
- **Find and Clear Rate is Approximately 61%**
- **SOP is to Employ a Ground Robot first**
- **Bomb Suits Only used When Terrain Prevents Robot Employment**

Training at 0900 hours



The robot “crew member” 6 hours later



JRRF-Iraq (Camp Victory)



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Monterey, CA

Approaches to Logistics

Yesterday (Mass-Based)



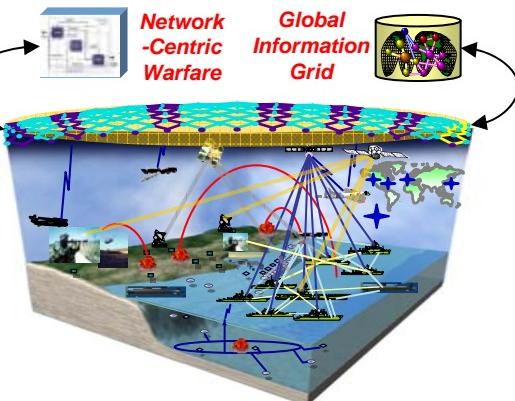
- More is better
- Mountains of stuff measured in days of supply
- Uses massive inventory to hedge against uncertainty in demand and supply
- Mass begets mass and slows everything down

Today (Just-in-Time)



- On-time is better
- Inventory is reduced to a minimum and kept moving
- Uses precise demand prediction and static optimization to purge uncertainty
- Works great, except when it doesn't

Tomorrow (Sense and Respond)



- Adaptive is better
- Inventory is dynamically positioned throughout
- Uses transportation flexibility and robust IT to handle uncertainty
- Initial S&R models look promising
- Supports distributed, adaptive ops

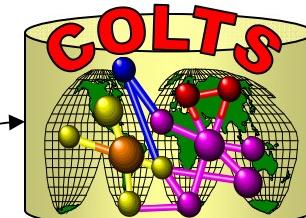
Prime Metric:
Days of Supply

Prime Metric:
Flow Time

Prime Metric:
Speed/Quality of Effects



Today's RSJPO approach
to COTS sustainment
tomorrow's Logistics
Knowledge-enabled, demand driven
Sense and Respond



Global Information

IUID & RFID +
COLTS = TAV

Interoperable joint
communications to the
tactical level

Real-time WEB based
WO's, TMs', TB's, and
history data facilitate the
S&R objectives

WEB-Based configuration
management result of
real-time structure
tracking and changing to
meet mission needs

All JRRF's have global
inventory view. Allowing for
Dynamically managed
inventories. Material can
be moved from closest
JRRF. Automated 1149

WEB based
application. All
organizations have
access. Interface
with WAWF and
DASSC possible

WEB technology provides
transaction transparency
and IT to minimize and
manage risk

Prime metric: Right material, right place, right time

It's all about Performance Based Logistics (PBL)

The Current (DAU) Definition:

PBL primary tenets are documentation of **WAR-FIGHTER** performance requirements as measurable metrics.

A fraction of the measurable metrics:

Operational Availability, Operational Reliability, Cost per Unit Usage, Total life cycle cost, Logistics Footprint, Logistics Response Time,

YADA, YADA, YADA



What Joint Robotics Repair & Fielding Is Doing

1. Define the **WAR-FIGHTER** : As the private or crew member in the heat of it.

2. Understand what is important to the **WAR-FIGHTER**:

Time

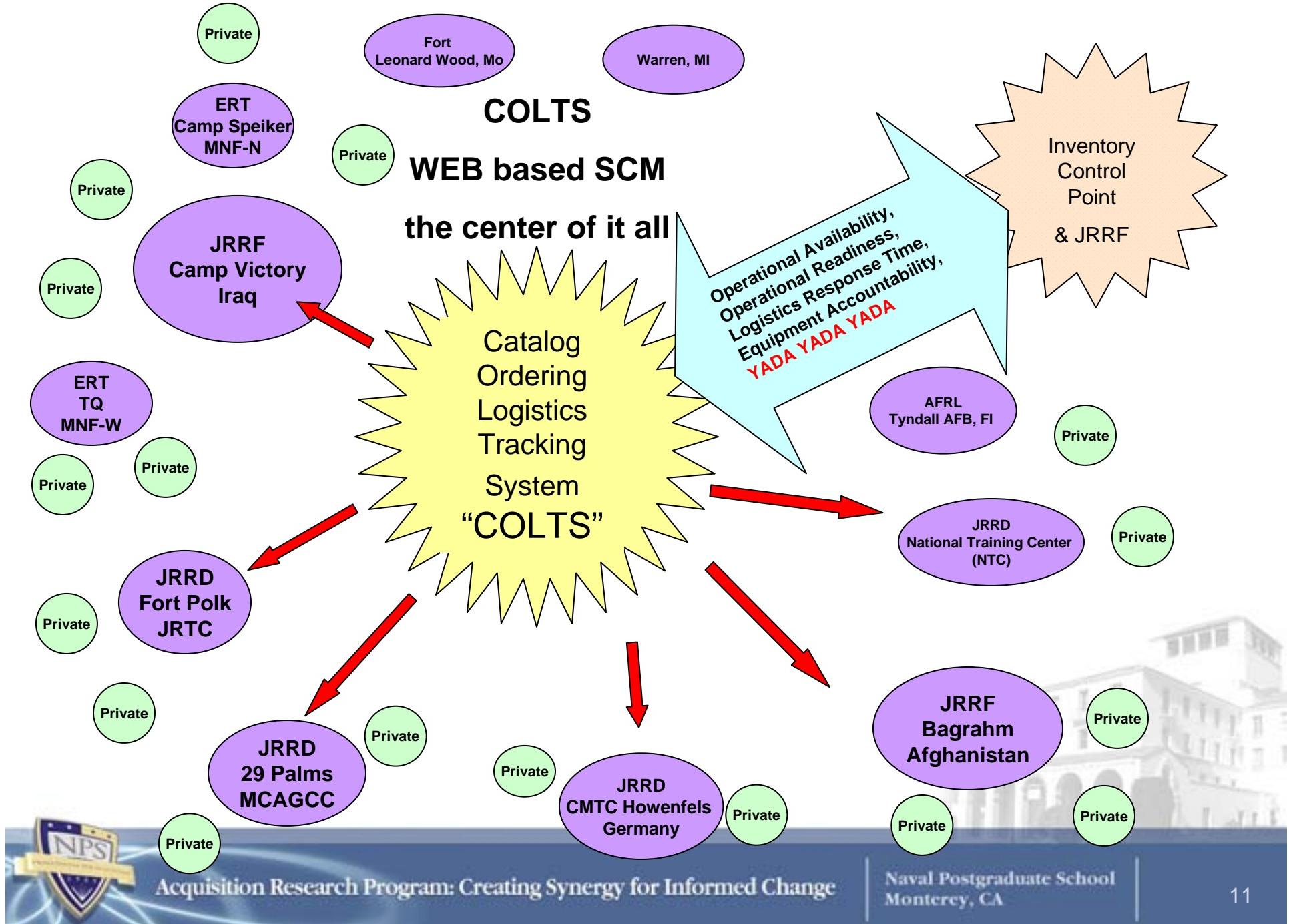
Equipment that works

Time

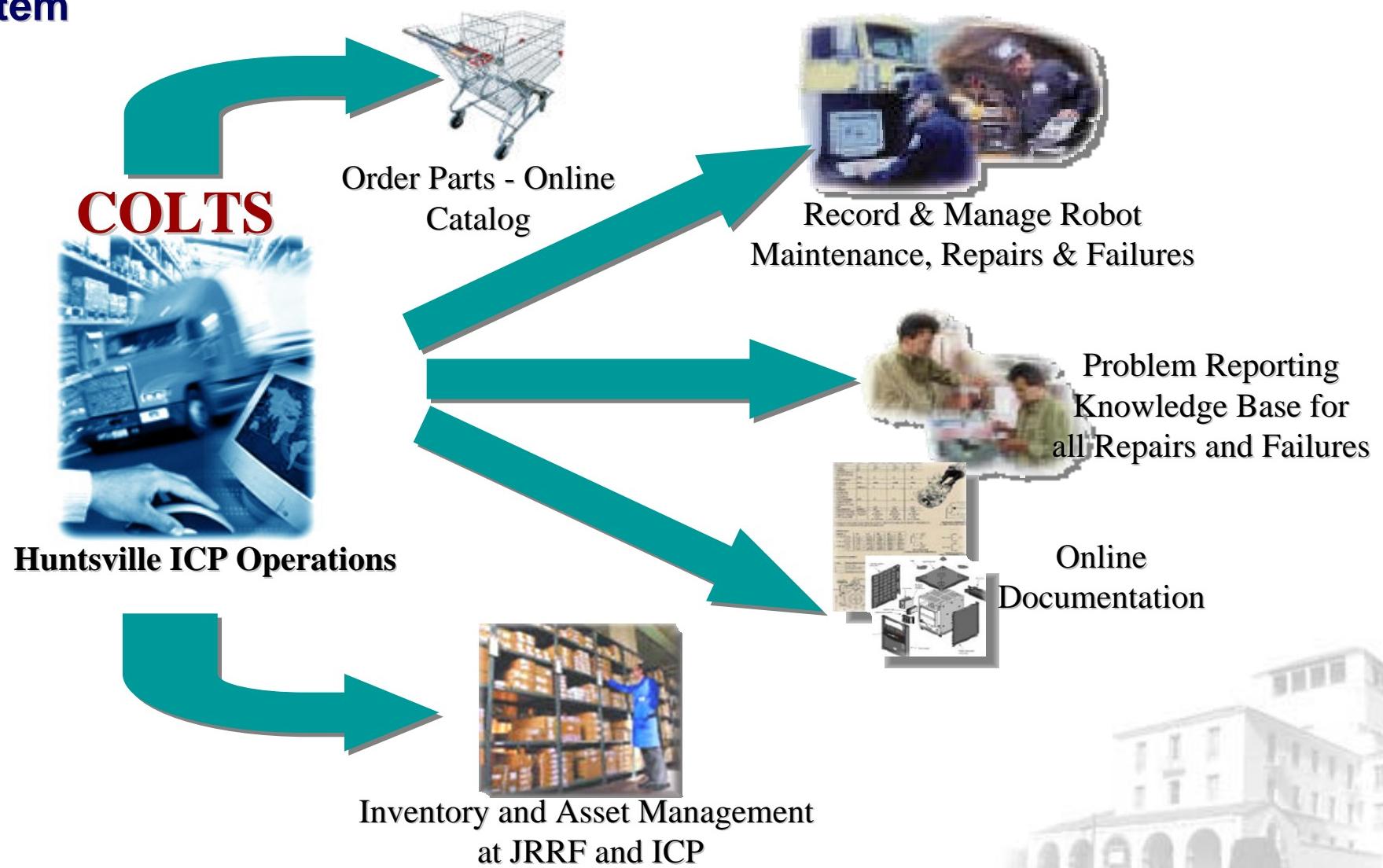
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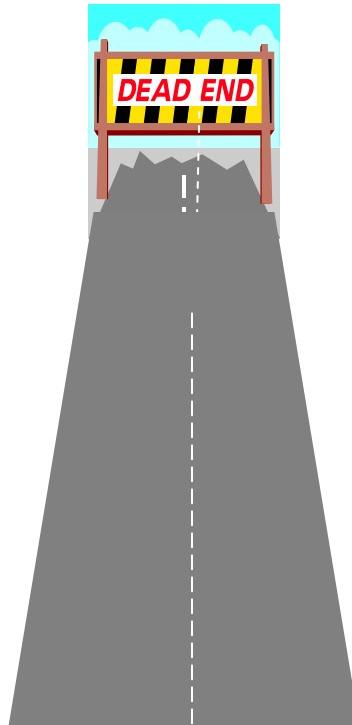


JRRF WEB Based-Supply Chain Management (SCM) System



Data (**IUID**) Don't just generate the data **USE** the data

COLTS Supply Chain Management



Implementing IUID without an integrated Supply Chain Management System is a Dead End.

But you will have met DoD requirements!

Your immediate gain will be

- ... No Savings
- ... No immediately usable data
- ... No incentive to comply
- ... No vendor “buy in”

The challenge is to find a way to implement IUID with your supply chain management system.

...RSJPO is using integrating IUID and our SCM



Making the Data work for you

Mandate and Goals

Under Secretary of Defense (USD) and Army's Product Manager, Joint Automatic Identification Technology (PMJAIT) require compliance with policy mandates for Unique Identification (UID) and Radio Frequency Identification (RFID) technologies for Supply Chain Management:

Mandate and Goals

Under Secretary of Defense (USD) and Army's Product Manager, Joint Automatic Identification Technology (PMJAIT) require compliance with policy mandates for Unique Identification (UID) and Radio Frequency Identification (RFID) technologies for Supply Chain Management:

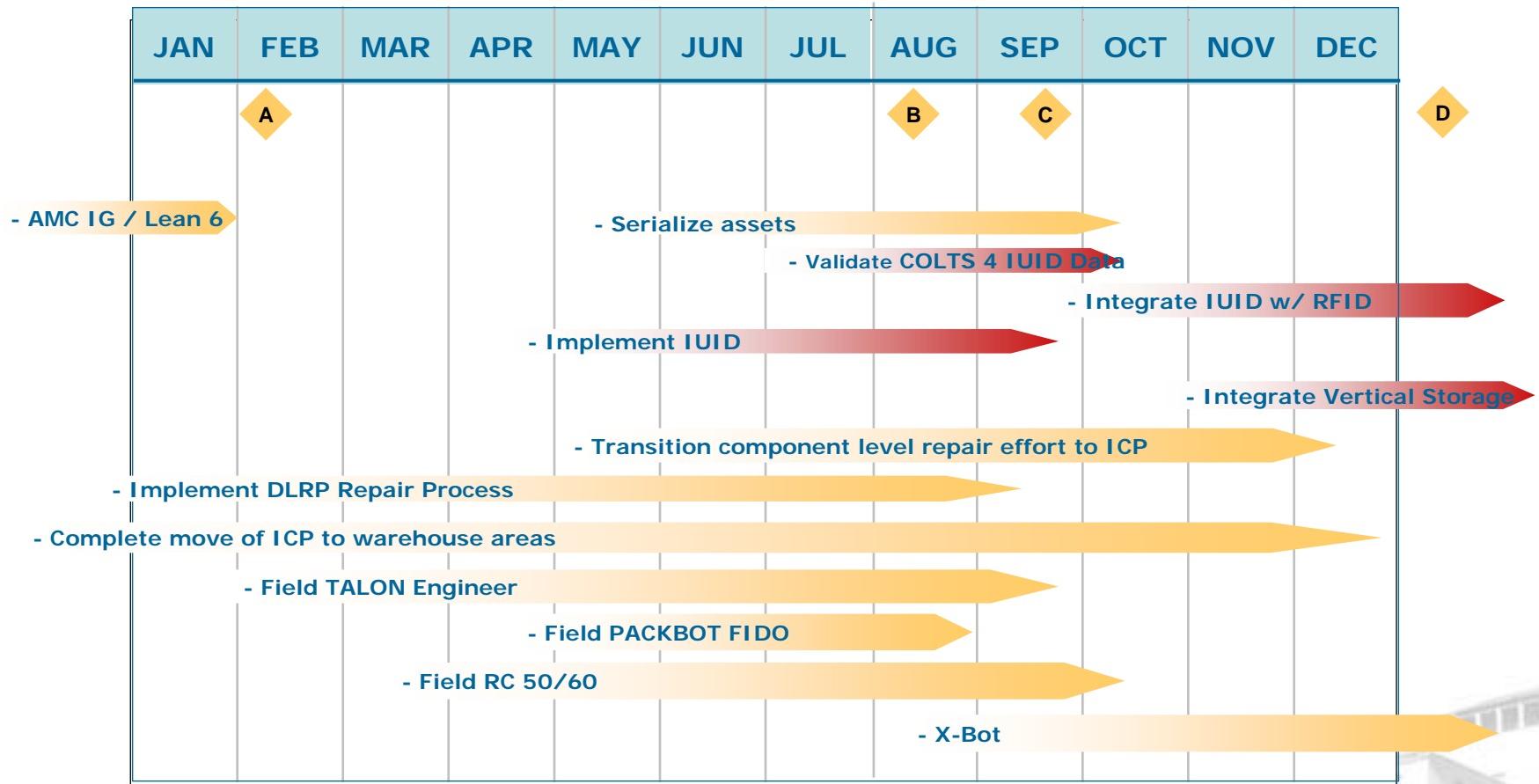
Critical to the End-to-End War fighter Support Initiative.

- Maximize efficiencies of life-cycle asset management with integration of UID/ RFID throughout DoD.
- Leverage technology to improve the ability to get the customer the right materiel, at the right time, and in the right condition
- Critical to the End-to-End War fighter Support Initiative.

Integrated Solution IUID and RFID Technologies With SCM



RSJPO Huntsville ICP 2007 Initiatives

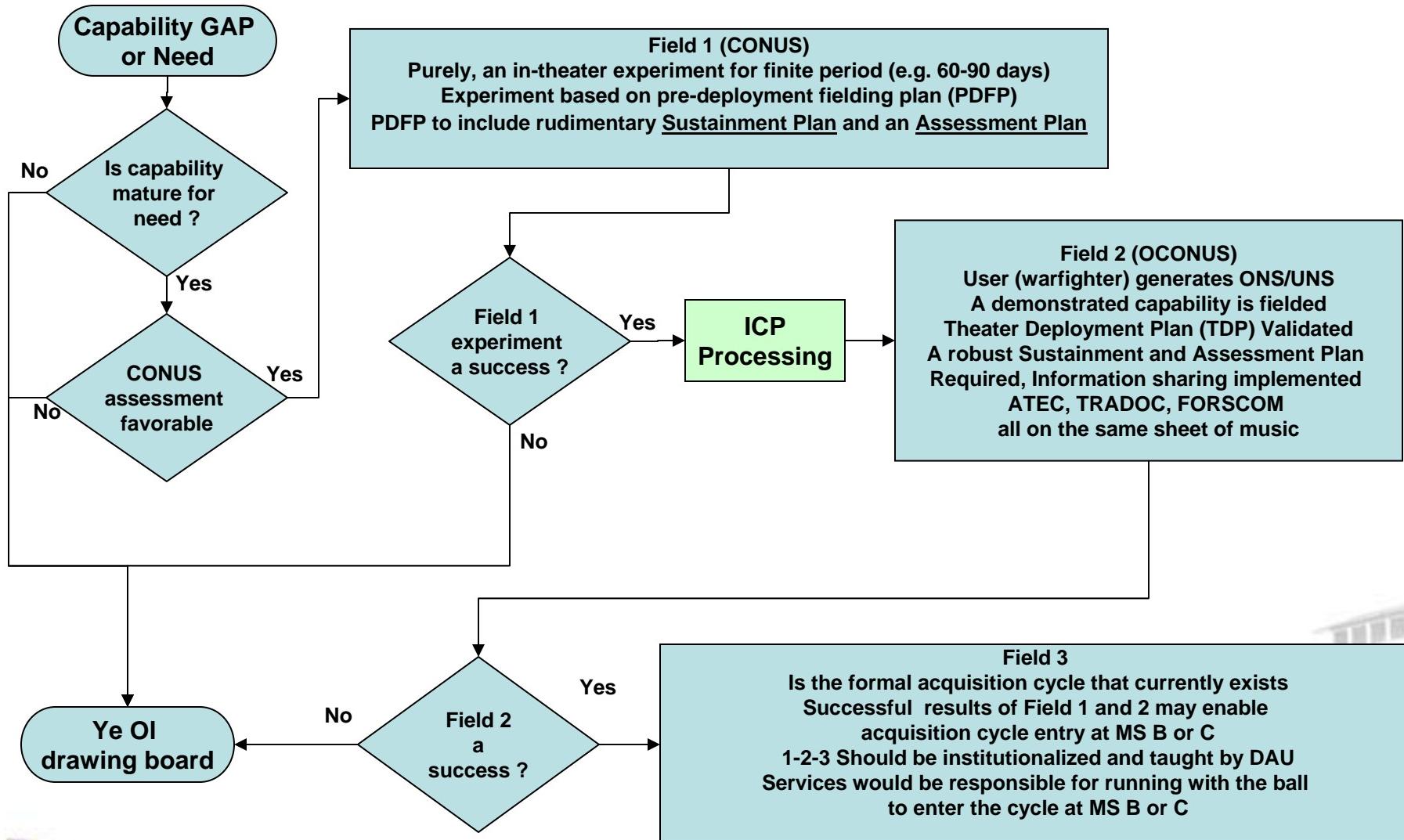


Milestones
 A: Survive AMC IG & Lean 6
 B: Transition to COLTS 4.4
 C: Fully implement IUID
 D: Combine RFID w/IUID

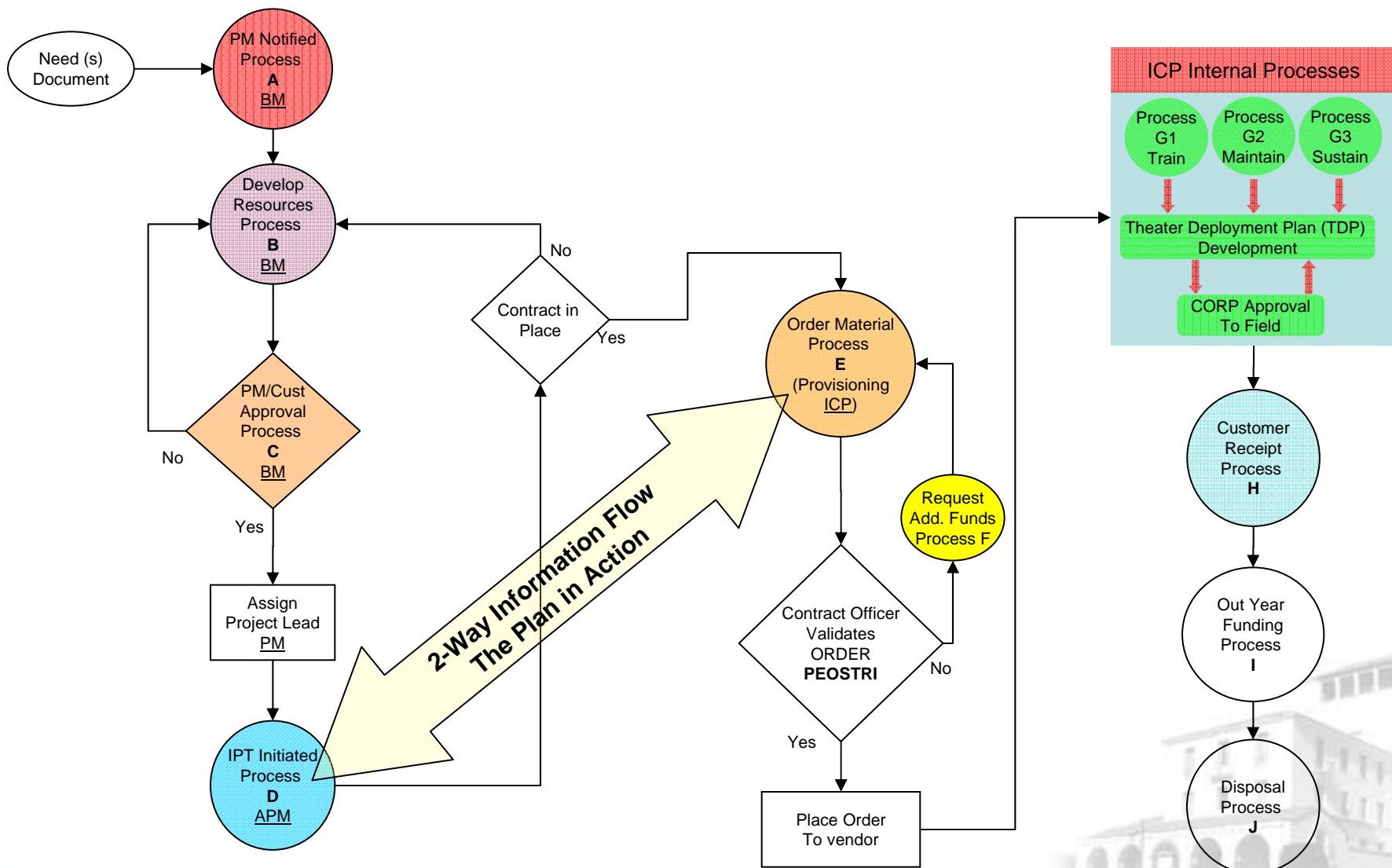
Significant Actions
 1: Transition to serialized accounting & SIM utilizing IUID as the common thread
 2: Implement DLRP Process
 3: Continue aggressive fielding and support
 4: IUID and COLTS integration completed in less than 5 months



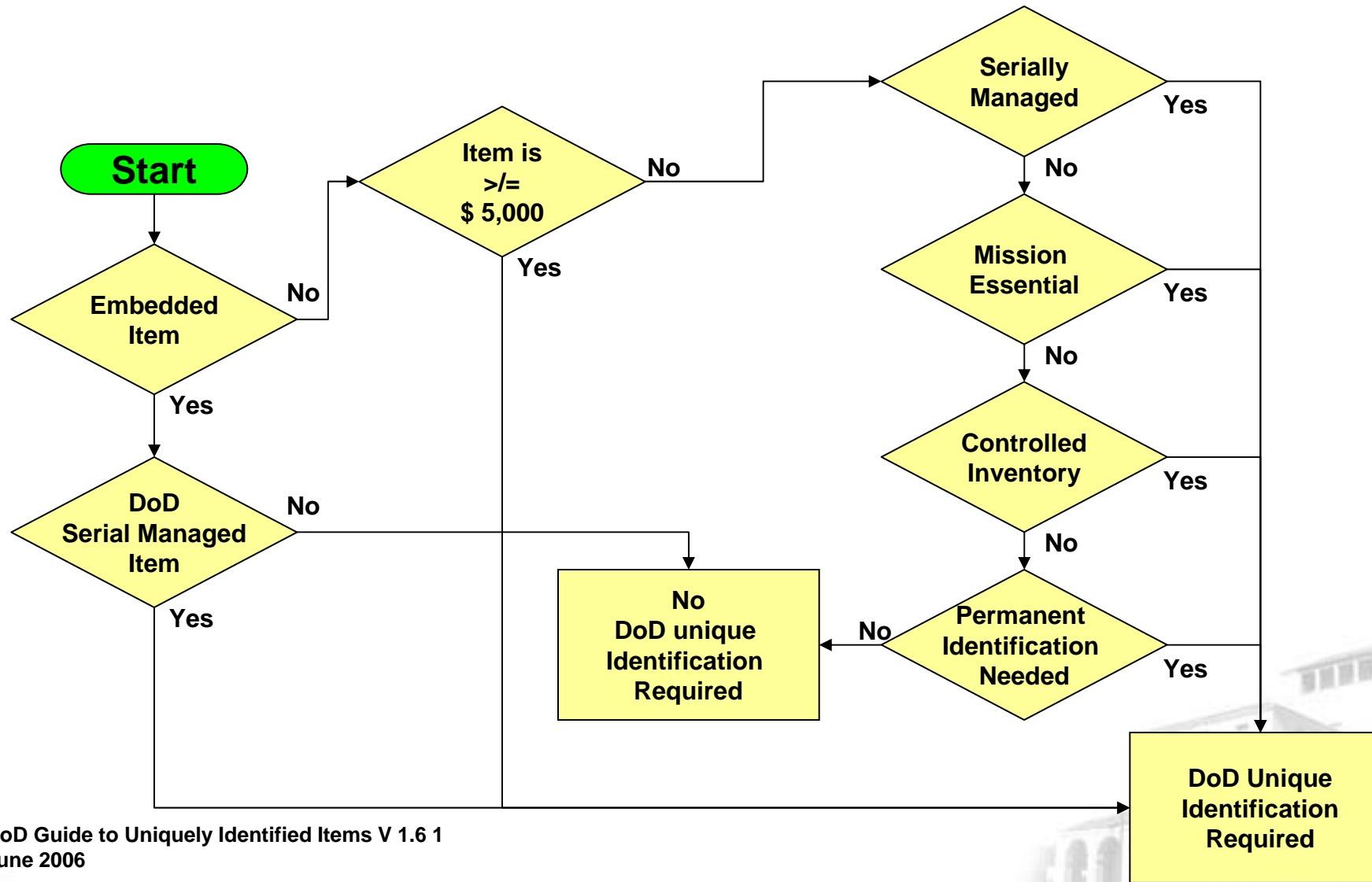
1,2,3, Process Flow



The JRRF from 40,000 feet



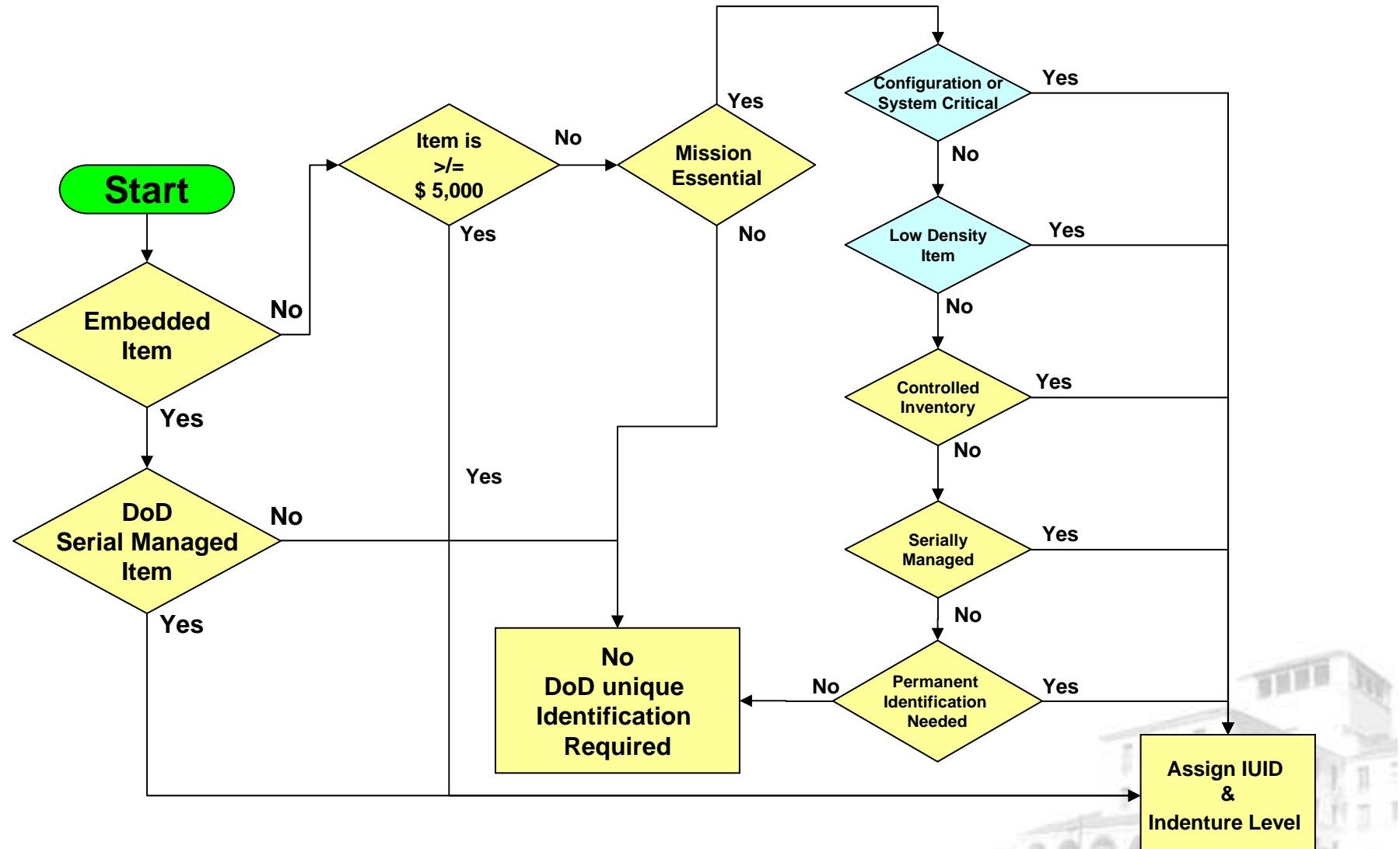
IUID Decision Flow Process



DoD Guide to Uniquely Identified Items V 1.6 1
June 2006



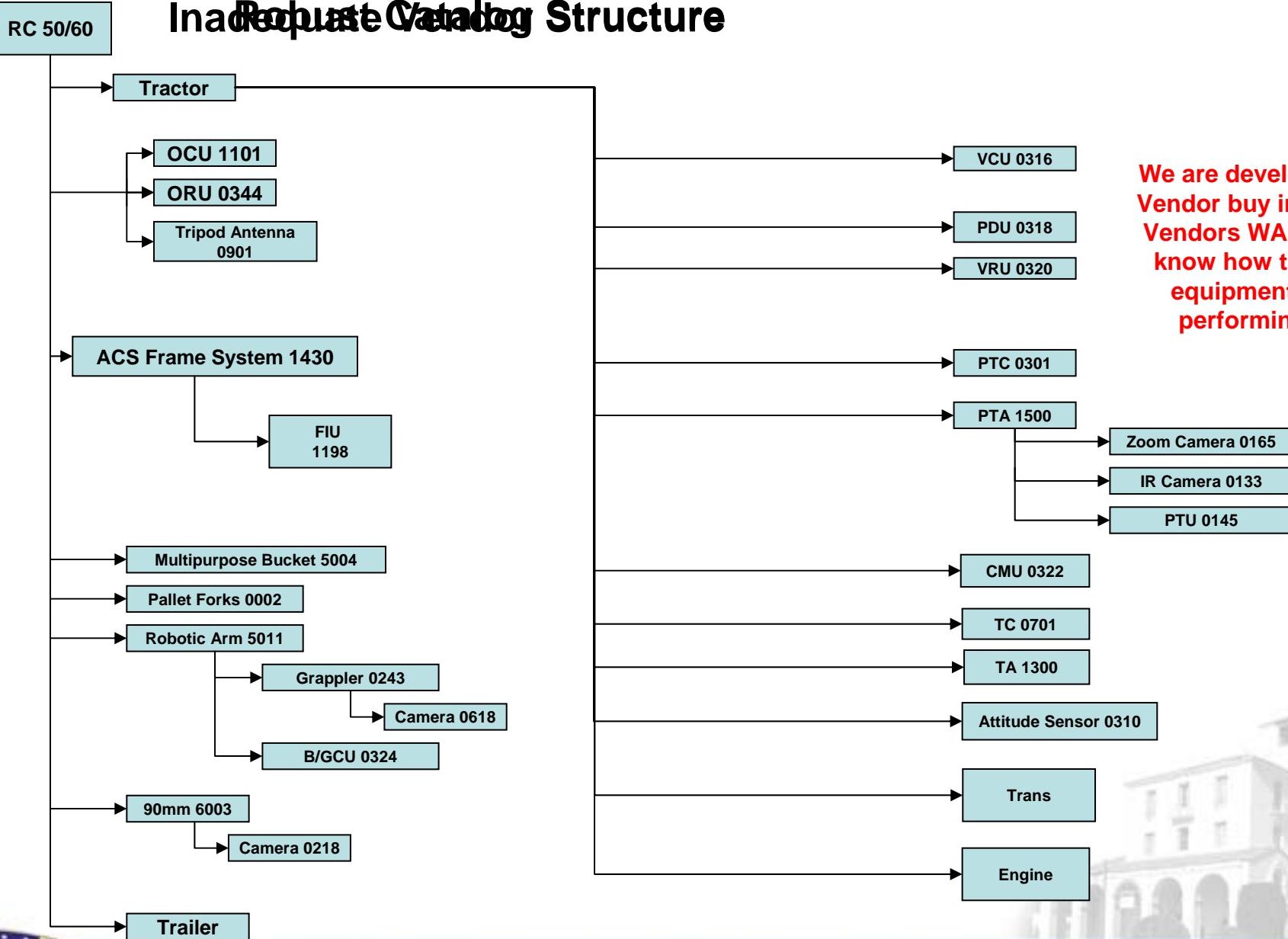
COLTS Catalog build process



RSJPO COLTS Catalog Build Decision Matrix



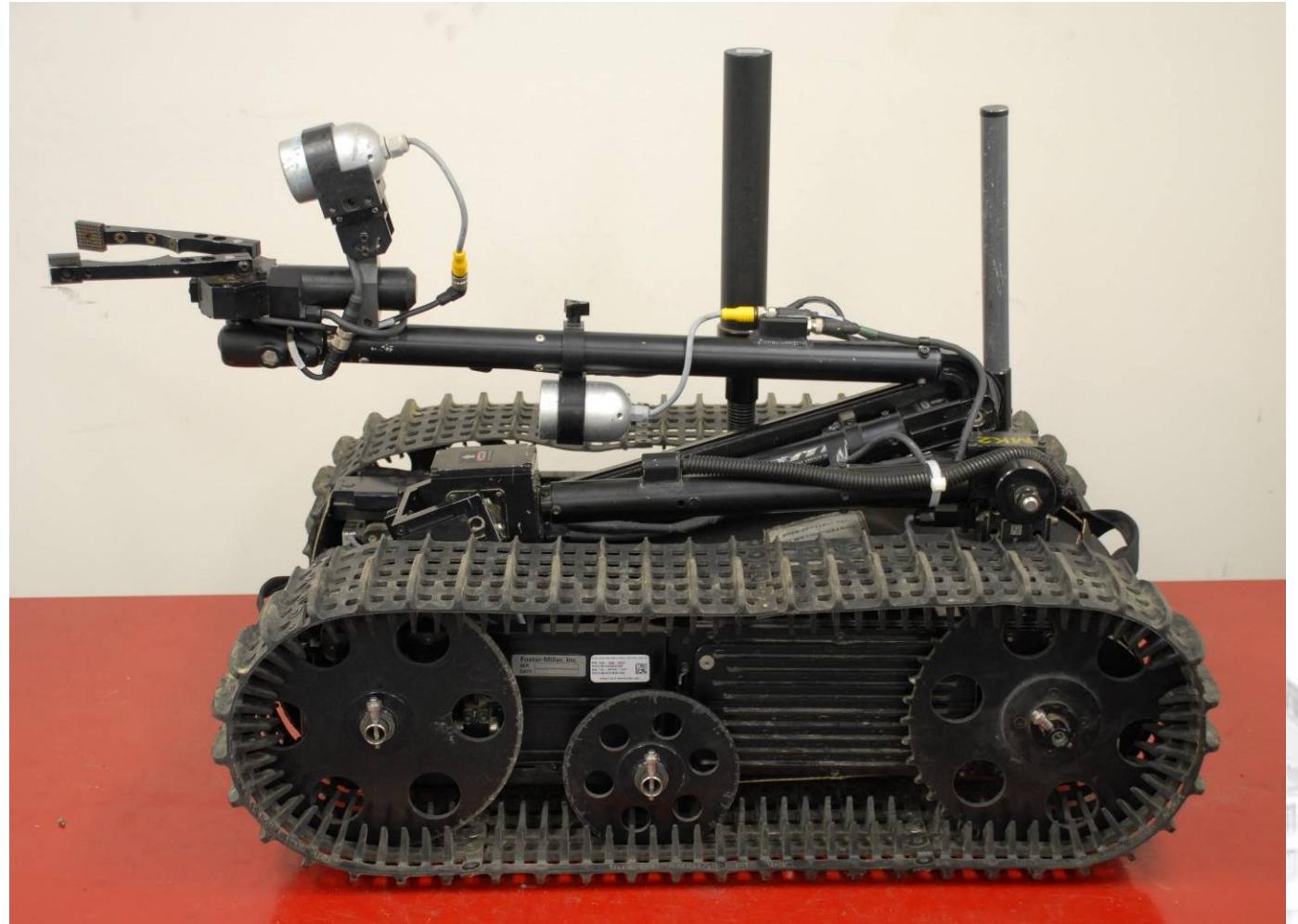
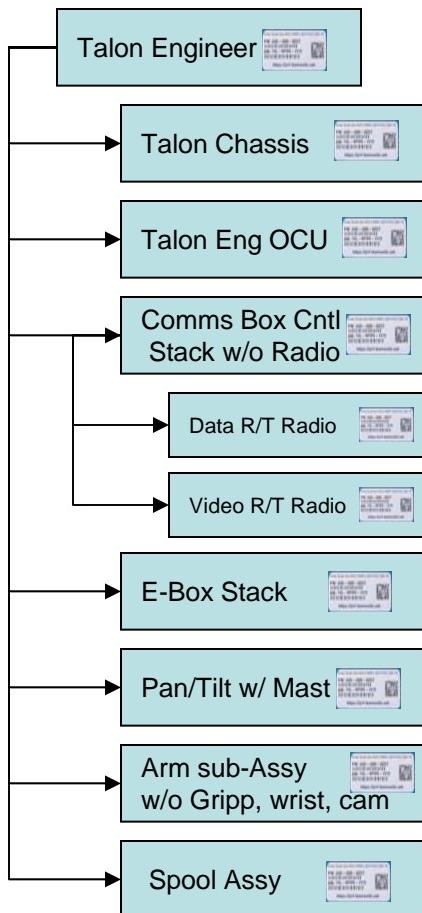
Inadequate Catalog Structure



We are developing Vendor buy in. The Vendors WANT to know how their equipment is performing.

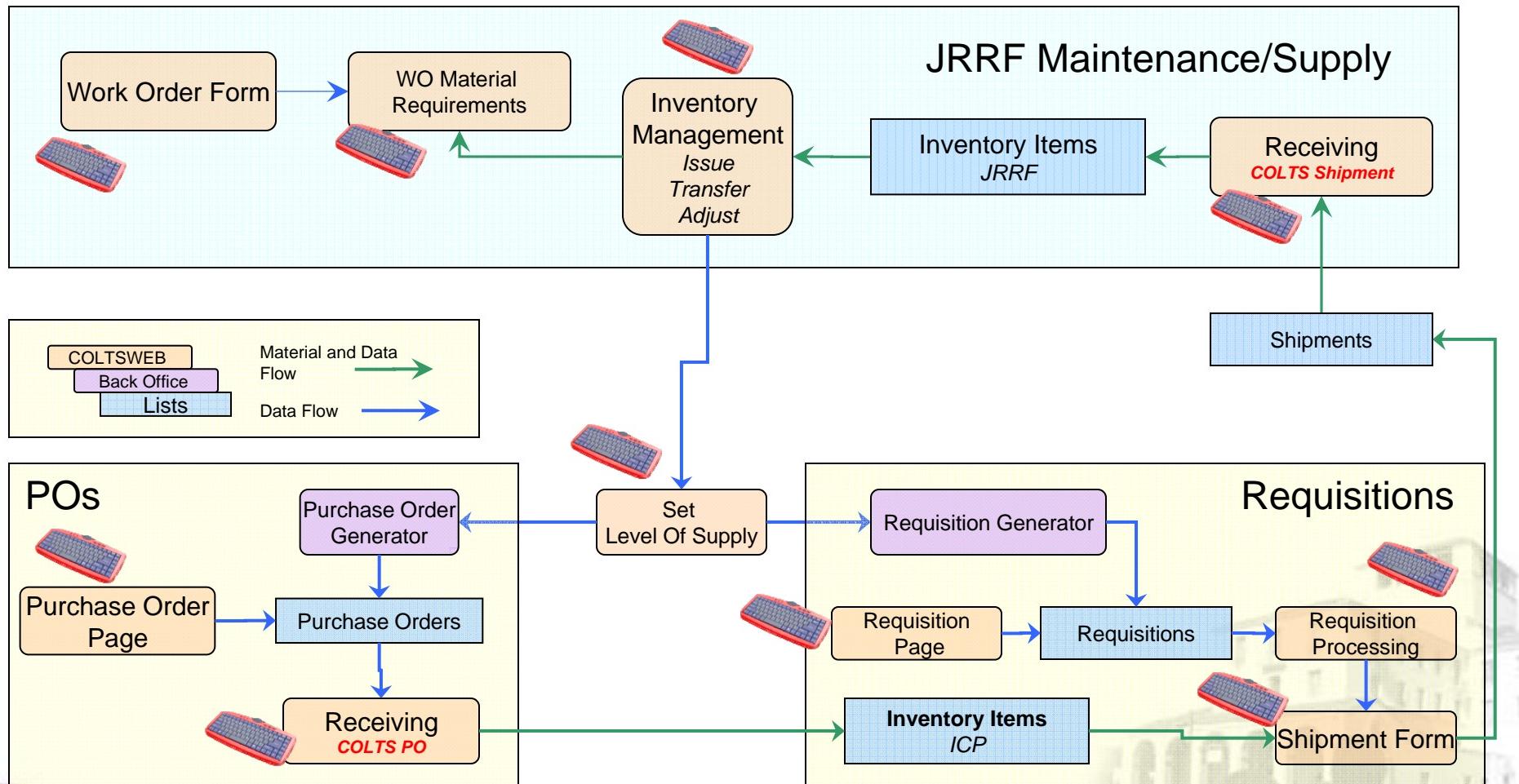


TALON 3B (Engineer and EOD Bot of Choice)



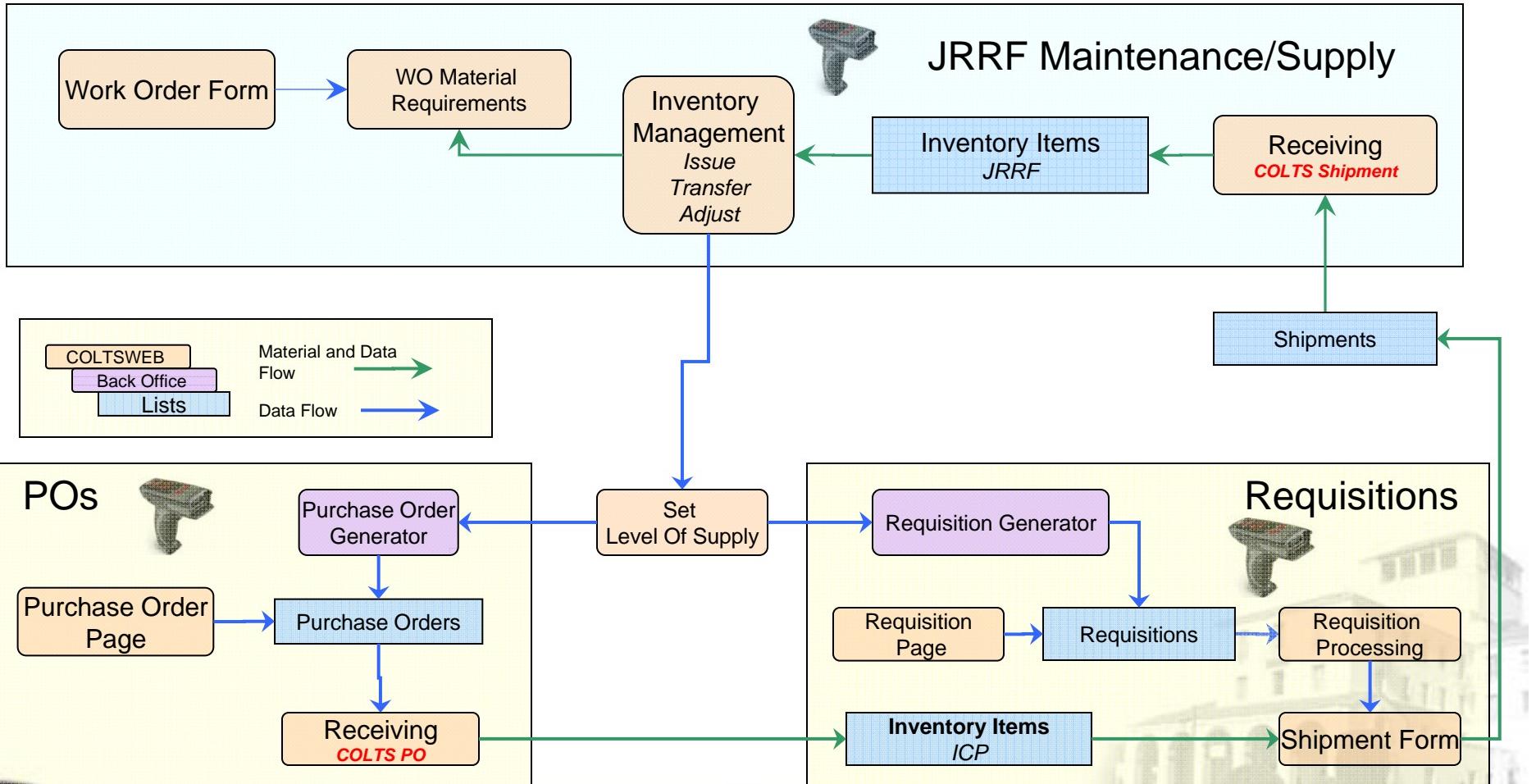
JRRF Prior to IUID integration

Each Keyboard represents opportunity for error



JRRF Prior to IUID integration

Each Scanner represent a process streamlined and error elimination.



IUID Pedigree Data Input

Enter Contact Information, Defaults and Output

COLTS 4.40 - MTRS

File Navigator Tools Window Help

UID Manager

Contact Information

| | |
|---------------|--------------------|
| Name: | Gerald Perlmutter |
| Email: | gerryp@avantix.com |
| Organization: | RS JPO |
| Phone: | 619.697.1166 |

Defaults

| | |
|--------------------|--------------|
| Enterprise Id: | 9999 |
| Issuing Agency Cd: | UN -- DUNS |
| UID Type: | UID2 |
| UID Medium Code: | 2D COMPLIANT |

Output

Generate UIDs:

Max Rows: 100 "0" If All Rows

Export Registry File:

<output XML file>

Print Run Close

UID Manager

Contact Information

| | |
|---------------|--------------------|
| Name: | Gerald Perlmutter |
| Email: | gerryp@avantix.com |
| Organization: | RS JPO |
| Phone: | 619.697.1166 |

Defaults

| | |
|--------------------|--------------|
| Enterprise Id: | 9999 |
| Issuing Agency Cd: | UN -- DUNS |
| UID Type: | UID2 |
| UID Medium Code: | 2D COMPLIANT |

Output

Generate UIDs:

Max Rows: 100 "0" If All Rows

Export Registry File:

<output XML file>

Print Run Close

Rows Visible: 8 of 10168 rows

| ID | UID IAC | UID Grade | UID Sent | UID Verify | UID Marked | UID Preassi |
|-----|---------|-----------|----------|------------|------------|-------------|
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App: MTRS Security:  COLTS 4.40.1025



IUID IUID & XML Generation

Export Registry File

COLTS 4.40 - MTRS

File Navigator Tools Window Help

UID Manager

Contact Information

| | |
|---------------|--------------------|
| Name: | Gerald Perlmutter |
| EMail: | gerryp@avantix.com |
| Organization: | RS JPO |
| Phone: | 619.697.1166 |

Defaults

| | |
|--------------------|--------------|
| Enterprise Id: | 9999 |
| Issuing Agency/Cd: | UN -- DUNS |
| UID Type: | UID2 |
| UID Medium Code: | 2D COMPLIANT |

Output

Generate UID's:

Max Rows: "0" If All Rows

Export Registry File:

C:\Documents and Settings\Gerald

Print **Run** **Close**

Display List **Search** **New List** **Current Row: 1**

| Site Stock | Site Name | Part Number | Description | N |
|------------|-------------------|--------------|---------------------|-----|
| DEPOT | 2ND EOD COMPANY | DSI-500-0042 | PAN AND TILT CAMERA | 166 |
| DEPOT | 2ND EOD COMPANY | DSI-500-0182 | VEHICLE BATTERY | 151 |
| DEPOT | 2ND EOD COMPANY | DSI-500-0227 | MK2 ROBOT VEHICLE | 166 |
| DEPOT | 2ND EOD COMPANY | DSI-500-0229 | COMMS BOX | 166 |
| DEPOT | 2ND EOD COMPANY | DSI-500-0257 | E BOX | 166 |
| DEPOT | 2ND EOD COMPANY | DSI-500-0278 | PAN TILT MAST | 166 |
| DEPOT | 2ND EOD COMPANY | DSI-500-0287 | OCS | 166 |
| DEPOT | 2ND EOD COMPANY | DSI-500-0369 | FIRE SET | 166 |
| DEPOT | 2ND EOD COMPANY | DSI-500-0398 | FIBER OPTIC SPOOLER | 166 |
| DEPOT | 2ND EOD COMPANY | DSI-500-0404 | Arm Assembly | 104 |
| DEPOT | 2ND EOD COMPANY | DSI-500-0406 | ARM ASSEMBLY | 170 |
| DEPOT | 2ND EOD COMPANY | RDSI-04209 | MK 2 BATTERY | 170 |
| DEPOT | 2ND EOD COMPANY | RDSI-04209 | MK 2 BATTERY | 173 |
| DEPOT | ARMY-184TH ORD BN | 10159 | BATTERY CHARGER KIT | 322 |
| DEPOT | ARMY-184TH ORD BN | 10159 | BATTERY CHARGER KIT | 322 |
| DEPOT | ARMY-184TH ORD BN | 10159 | BATTERY CHARGER KIT | 322 |
| DEPOT | ARMY-184TH ORD BN | 10159 | BATTERY CHARGER KIT | 322 |
| DEPOT | ARMY-184TH ORD BN | 10159 | BATTERY CHARGER KIT | 322 |
| DEPOT | ARMY-184TH ORD BN | 10159 | BATTERY CHARGER KIT | 322 |
| DEPOT | ARMY-184TH ORD BN | 10159 | BATTERY CHARGER KIT | 322 |
| DEPOT | ARMY-184TH ORD BN | 12130 | CHASSIS (VEHICLE) | 001 |
| DEPOT | ARMY-184TH ORD BN | 12130 | CHASSIS (VEHICLE) | 001 |
| DEPOT | ARMY-184TH ORD BN | 12130 | CHASSIS (VEHICLE) | 001 |
| DEPOT | ARMY-184TH ORD BN | 12130 | CHASSIS (VEHICLE) | 001 |
| DEPOT | ARMY-184TH ORD BN | 12130 | CHASSIS (VEHICLE) | 001 |
| DEPOT | ARMY-184TH ORD BN | 12130 | CHASSIS (VEHICLE) | 001 |
| DEPOT | ARMY-184TH ORD BN | 12131 | OCS Assembly | 002 |
| DEPOT | ARMY-184TH ORD BN | 12131 | OCS ASSEMBLY | 002 |
| DEPOT | ARMY-184TH ORD BN | 12131 | OCS ASSEMBLY | 002 |
| DEPOT | ARMY-184TH ORD BN | 12131 | OCS ASSEMBLY | 002 |
| DEPOT | ARMY-184TH ORD BN | 12131 | OCS ASSEMBLY | 002 |
| DEPOT | ARMY-184TH ORD BN | 12131 | OCS ASSEMBLY | 002 |
| DEPOT | ARMY-184TH ORD BN | 4975 | Manipulator [Arm] | 016 |
| DEPOT | ARMY-184TH ORD BN | 4975 | MANIPULATOR (ARM) | 016 |
| DEPOT | ARMY-184TH ORD BN | 4975 | MANIPULATOR (ARM) | 016 |
| DEPOT | ARMY-184TH ORD BN | 4975 | MANIPULATOR (ARM) | 016 |
| DEPOT | ARMY-184TH ORD BN | 4975 | MANIPULATOR (ARM) | 016 |

< >

Views: Active Assets

```
<?xml version="1.0" encoding="utf-8" ?>
<UidDocument>
  <LegacyOrNewCode>LEGACY</LegacyOrNewCode>
  <Version>3.3</Version>
  <Contact>
    <Email>gerryp@avantix.com</Email>
    <Name>Gerald Perlmutter</Name>
    <Organization>RS JPO</Organization>
    <Phone>619.697.1166</Phone>
  </Contact>
  <AddItem>
    - <EndProduct>
      - <ContractInfo>
        <Description>FIRE SET</Description>
        - <UidList>
          <EnterpriseIdentifier>9999</EnterpriseIdentifier>
          <IssuingAgencyCode>UN</IssuingAgencyCode>
          <OriginalPartNumber>DSI-500-0369</OriginalPartNumber>
          <SerialNumber>1661</SerialNumber>
          <Uid>UN9999DSI-500-03691661</Uid>
          <UidType>UID2</UidType>
        - <Mark>
          <BaggedOrTaggedCode>N</BaggedOrTaggedCode>
          <Contents>UID</Contents>
          <EffectiveDate>2007-08-27</EffectiveDate>
          <AddedOrRemovedCode>A</AddedOrRemovedCode>
          <MarkerCode>UN</MarkerCode>
          <MarkerIdentifier>9999</MarkerIdentifier>
          <MediumCode>2D COMPLIANT</MediumCode>
        </Mark>
      </UidList>
    </ContractInfo>
  </EndProduct>
  - <EndProduct>
    - <ContractInfo>
      <Description>FIBER OPTIC SPOOLER</Description>
      - <UidList>
        <EnterpriseIdentifier>9999</EnterpriseIdentifier>
        <IssuingAgencyCode>UN</IssuingAgencyCode>
        <OriginalPartNumber>DSI-500-0398</OriginalPartNumber>
        <SerialNumber>1661</SerialNumber>
        <Uid>UN9999DSI-500-03981661</Uid>
        <UidType>UID2</UidType>
      - <Mark>
        <BaggedOrTaggedCode>N</BaggedOrTaggedCode>
        <Contents>UID</Contents>
        <EffectiveDate>2007-08-27</EffectiveDate>
        <AddedOrRemovedCode>A</AddedOrRemovedCode>
        <MarkerCode>UN</MarkerCode>
        <MarkerIdentifier>9999</MarkerIdentifier>
        <MediumCode>2D COMPLIANT</MediumCode>
      </Mark>
    </UidList>
  </ContractInfo>
  </EndProduct>
  - <EndProduct>
    - <ContractInfo>
      <Description>Arm Assembly</Description>
      <UidList>
```



IUID Printing options

Print

Suggested Low Cost Printer Suite

| Printer Type | Label Description | Equipment Cost | Label Cost |
|-----------------|----------------------------------|----------------------|---------------|
| Universal Laser | Tesa Tape and metal label plates | ~ \$20,000 equipment | 14 cents each |
| Printronix | 4" X 2" labels and RFID tags | ~ \$ 5,000 equipment | 5 cents each |
| Zebra | Mylar labels | ~ \$3,000 equipment | 4 cents each |

IUID Data Verification Process

Verify

COLTS 4.40 - MTRS

File Navigator Tools Window Help

UID Manager

Contact Information

- Name: Gerald Perlmuter
- Email: gerryp@avantix.com
- Organization: RS JPO
- Phone: 619.697.1166

Defaults

- Enterprise Id: 9999
- Issuing Agency Cd: UN -- DUNS
- UID Type: UID2
- UID Medium Code: 2D COMPLIANT

Output

- Generate UIDs:
- Max Rows: "0" If All Rows
- Export Registry File:
- Koutput XML file:

Print Run Verify Close

Asset UID Grade

| | | | |
|--------------|-----------------------------|------|------|
| Part Number: | DSI-500-0227 | S/N: | 1661 |
| IUID: | UN999999999DSI-500-02271661 | | |
| Description: | MK2 ROBOT VEHICLE | | |

Scan successful

Details Label Placement Instructions Additional Fields and Flags

Date Graded: 8/28/2007 11:51:04 AM

Device Type: COGNEX DM7500

| Grade | Parameter Value |
|-----------------------|-----------------|
| UID Grade: | DPM4/13/639/30T |
| Angle Distortion: | |
| Axial Non-Uniform: | A +0.009 |
| Cell Contrast: | A +0.812 |
| Cell Growth Horiz: | +19.547 |
| Cell Growth Vertical: | +19.505 |
| Cell Modulation: | A |
| Fixed Pattern Dmg: | A |
| Grid Non-Uniform: | A +0.084 |
| Min Reflect: | A 81 |
| Reference Decode: | A |
| Unused ECC: | A +1.000 |

Ready Clear All Update Close

COLTS 4.40.1026



IUID Marking Instructions

Step Six: Secure Label

The screenshot shows the COLTS Part Form application in Microsoft Internet Explorer. The main window displays the 'MTRS Part' configuration screen. In the bottom left, there's a 'Labeling Instructions' section with a yellow highlighted area. A hand is shown applying a label to a mechanical component, likely a track system, in the background image. Lines from the yellow highlighted area point to both the text and the image.

MTRS Part

Part Number: DSI-500-0227
Supplier Name: FOSTER-MILLER CAGE: 08KG1
Description: MK2 ROBOT VEHICLE
System: MK2 MODO
Cognizance Code:
UID Type: Catalog Price: 131900
Hazardous Code:
Serialized: Exclude From Tracked Configurations:
FSC: UID IAC: UM: each
Shelf Life Code: Sch B Exp Cd:
Can Req: Controlled: Inactive: Mission Critical:
NIIN: UID EID:
Shelf Life Action Code:

Alternates **IUID Label Placement** Additional Fields

IUID Figure:
Labeling Instructions: Place the label on left side of Rd below top track

Save Close

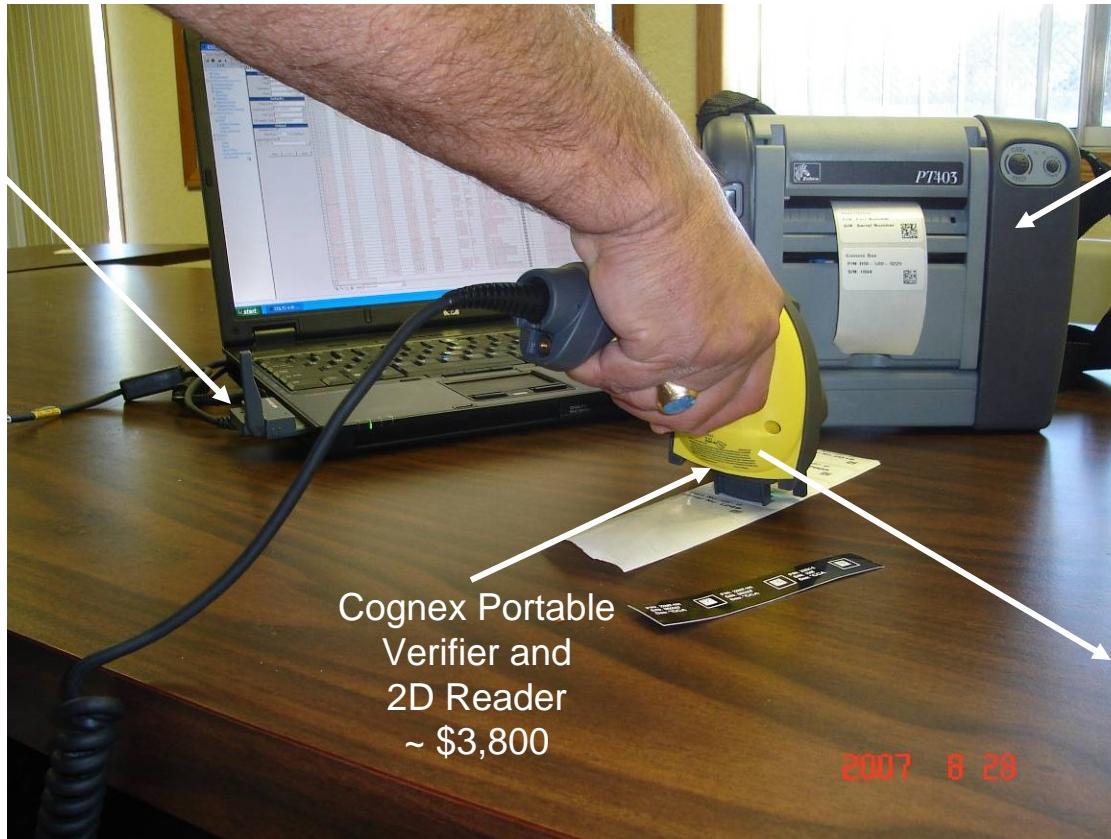
Done Local intranet

<http://localhost/colts4i/Pics/Scanner Pic1.JPG> - Microsoft Internet Explorer



IUID Portable On-Site Suite

Air Card for off site
Citrix connection to
SCM Server
\$60/month



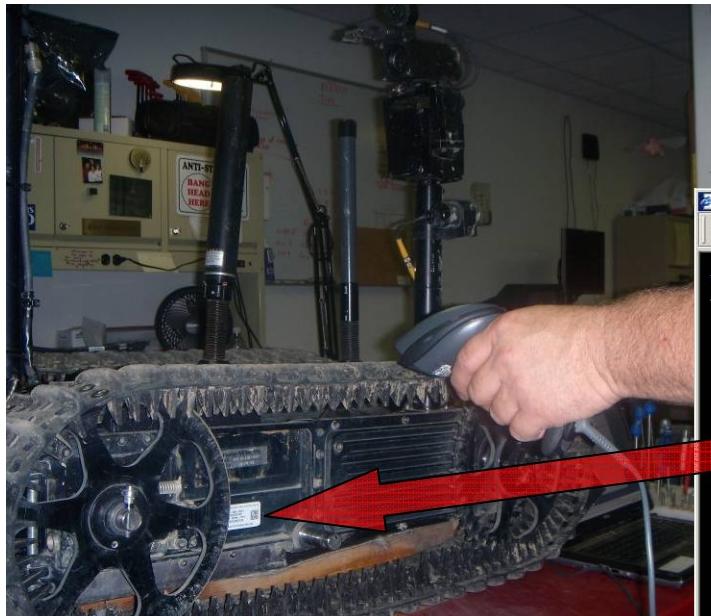
Zebra PT403
Portable Rugged
Printer
2" x 1" Mylar
~ \$1000 each

Note: this Verifier
is NMCI compatible
and does not need
special software.



IUID and Maintenance

Maintenance Management



COLTS 4i Work Order - Microsoft Internet Explorer

You have new notifications

Inventory Menu Logout Help My Profile

Reason for WO: PTM TILT INOP

WO: REP-JRRF_IRAQ

Item Under Repair [Lookup](#)

Date Reported: 3/15/2007 4:34:50 AM

IUID: UN9999DSI-500-02271151

Site: REP-JRRF_IRAQ

Part #: DSI-500-0227

Date Occurred: 3/15/2007 4:34:50 AM

Serial #: 1151

Failure Site: Not Specified

Description: MK2 ROBOT VEHICLE

Condition: A--RFT

Component Detail

Detailed Description Maintenance Actions Material Requirements Contact Information Additional Information Mod Checklist

Detailed Description: PTM TILT INOP

Status: Ready For Issue

Work Order Type: C--Corrective

Closed: 3/15/2007 4:45:31 AM

Last Assigned To: Charles.Emery.Burns

Time To Repair: 0

Site: DEP-FM

List By: WorkOrder # Assigned To/Opened By You

Serial Number All Open This Site

New 00003267 [Look Up](#)

New 00003304

Save Close

Done Local intranet

One Scan opens a Work Order
and transfers equipment for
Asset and Property Book
Management.



IUID and Supply & Shipping

Shipping, Receiving & Inventory Management



Scan to identify issued inventory

MTRS Inventory
Work Order Material Requirements
WO: 00003234 Item Under Repair: MK2 ROBOT VEHICLE

| Action | Type | Qty | Description | Part Number | Serial Number | Req No | Date |
|--------|-------------|-----|-------------|--------------|---------------|--------|---------------------|
| X | Replacement | 1 | E BOX | DSI-500-0257 | 1469 | | 8/7/2007 7:32:07 AM |
| X | Replacement | 1 | E BOX | DSI-500-0257 | 1478 | | 8/7/2007 7:53:21 AM |

Inventory Items

| Item | Quantity Available | Alt | Description | Part Number | Supplier Name | Loc Code | Serial Number | Condition Code |
|------------------|--------------------|-----|--------------|--------------|---------------|----------|---------------|----------------|
| + Add a new item | | | | | | | | |
| 1 | 10 | | ARM ASSEMBLY | DSI-500-0406 | FOSTER-MILLER | MAINT | (10) | |
| 2 | 3 | | ARM ASSEMBLY | DSI-500-0406 | FOSTER-MILLER | N/A | (8) | |
| 3 | 1 | | ARM ASSEMBLY | DSI-500-0406 | FOSTER-MILLER | SUPPL | (12) | |

End Of List

Work Orders at Site
00003234

Part Search

| Description | Part Number | Serial Number | IUID | Supplier | System |
|-------------|--------------|---------------|------|----------|--------|
| | dsi-500-0406 | | | Any | Any |

List Configuration Options

Site: REP-JRRF IRAQ Show Serial Numbers Work Order View Exact Match
Class: DEPOT Most Frequently Used History View Show Alternates

Views Search Options

Select Close Local intranet

Scan to identify issued inventory, items shipped (DD1149), and Items received.



Scan to ID items shipped & Received (DD1149)



Just the facts (1 Jan 07 – 31 Dec 07)

- COLTS Supply & Maintenance Data
 - 6073 Work orders completed
 - 26,375 maintenance actions
 - 64,419 Inventory events (Parts movement)
 - 78,467 Asset events (Robot actions/movement/repair, etc)
 - 4,816 Items shipped
 - 64 EOD/Engineer robots rebuilt from a destroyed condition. Cost savings approximately 3.2 million dollars.
- AIT, IUID/RFID integration saves the RSJPO time, money and ultimately lives on the battlefield.
 - No more “lost” data due to human error
 - Shorter repair cycle time as a result of IUID “scan in & scan out”
 - More fidelity of data tracked in COLTS due to IUID decision process.
 - Routine logistics processes streamlined with IUID and hand scanner.
 - Configuration management integrated with all SCM actions. SIM is a reality
- Operational rate on all NS-E/COTS supported platforms has been in excess of 98% since Apr 05.
- In excess of 3307 soldiers trained on robotics operation



Return on Investment

- A misplaced hyphen cost \$280K
- IUID enables Serialized Item Maintenance (SIM is a DoD Mandate)
 - IUID Enables real time configuration management
 - IUID Saves repair parts cost
 - Aug 06-Mar 07 \$29M for repair parts on 1 vendor
 - Aug 07-Mar 08 \$ 5M for repair parts on same vendor
- IUID eliminates human induced error
 - Average human has a typing error rate 5.47%. For every 100 key strokes 6 will be wrong

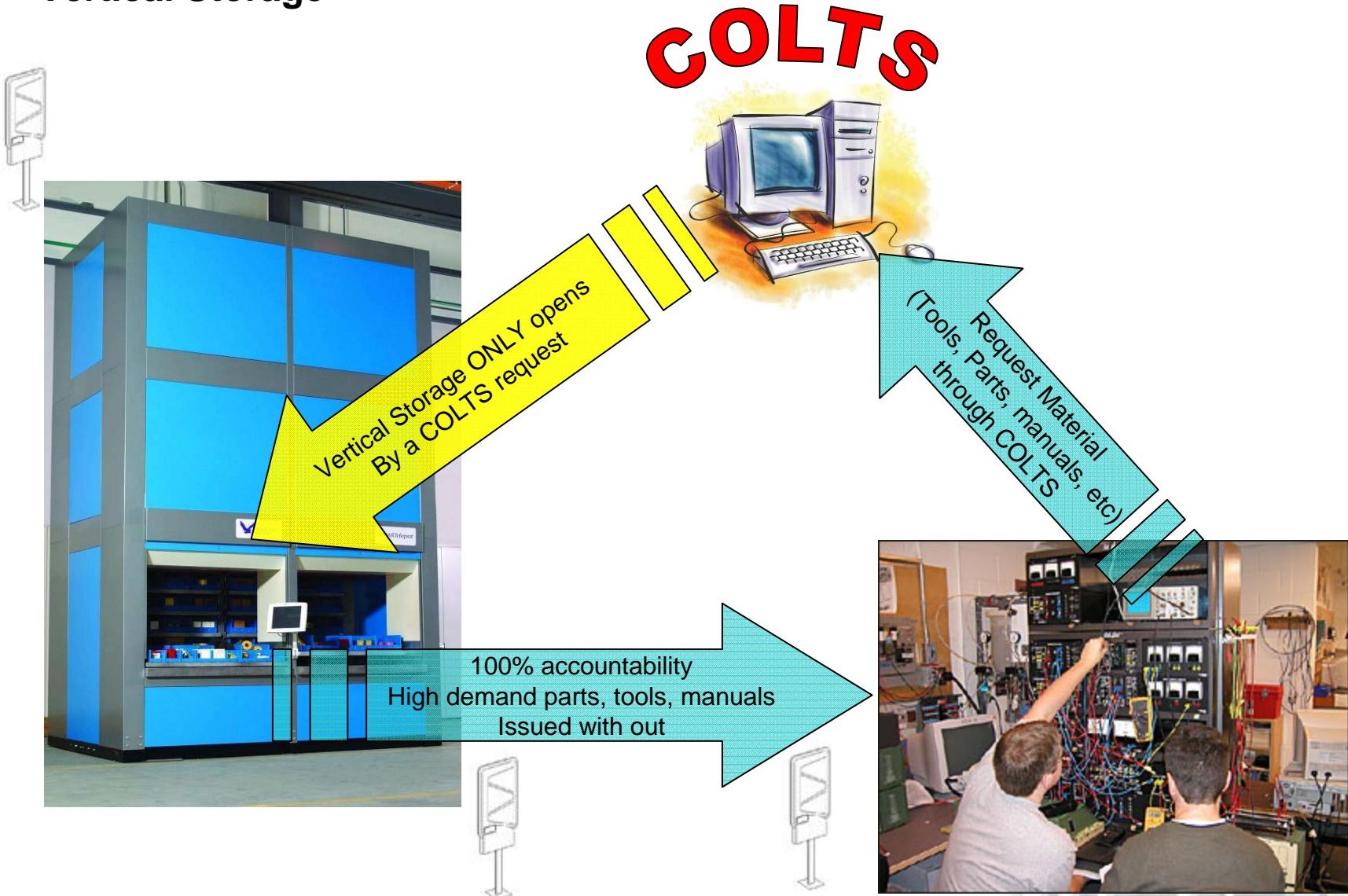


Future Operations; Where we are going

- Vertical storage (Self Issue) (Feb 2008)
 - 100% automated accountability COLTS opens the drawer not the user
 - High use items will be co-located with technicians
 - Tool room functions
- Integrated RFID (Apr 2008)
 - End items will receive active (aRFID) / (pRFID) passive permanent RFID
 - ICP will utilize aRFID / pRFID to streamline operations
- Integrate CBM+ (Conditioned Based Maintenance)
 - We want the robots to tell us (JRRF) when they need service
- Institutionalize the JRRF process for NS-E/COTS sustainment
 - Establish a Joint Service approach
 - Staff and train a Joint Reserve organization to be reactive to mobilization and NS-E/COTS support (Train, Maintain, Supply)
 - Stop inventing the wheel at every conflict. Institutionalize the innovative process



Vertical Storage



Questions?

